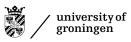
Langevin Dynamics

A Continuous and Discrete Analysis

D. Cortild, F. Voronine

Faculty of Science and Engineering University of Groningen

BB 5161.0165, January 23rd, 2024





mathematics and applied mathematics



Preliminaries

Let X be a random variable on a probability space $(\mathbb{R}^n, \mathcal{B}, \mathbb{P})$.

Reminder of Probability Theory

Let X be a random variable on a probability space $(\mathbb{R}^n, \mathcal{B}, \mathbb{P})$.

• The **probability density** of the random variable $X \sim \mu$ is a function $\rho: \mathbb{R}^n \to \mathbb{R}$ such that

$$\int_A \rho(x) dx = \mathbb{P}(X \in A) = \mu(A).$$

Reminder of Probability Theory

Preliminaries

Let X be a random variable on a probability space $(\mathbb{R}^n, \mathcal{B}, \mathbb{P})$.

• The **probability density** of the random variable $X\sim \mu$ is a function $\rho:\mathbb{R}^n\to\mathbb{R}$ such that

$$\int_{A} \rho(x) dx = \mathbb{P}(X \in A) = \mu(A).$$

• Various notions of **statistical distance** can be defined on the space of probability measures. Examples include the Wasserstein 2-norm, the χ^2 -divergence and the KL-divergence

Reminder of Probability Theory

Let X be a random variable on a probability space $(\mathbb{R}^n, \mathcal{B}, \mathbb{P})$.

• The **probability density** of the random variable $X \sim \mu$ is a function $\rho: \mathbb{R}^n \to \mathbb{R}$ such that

$$\int_A \rho(x) dx = \mathbb{P}(X \in A) = \mu(A).$$

• Various notions of **statistical distance** can be defined on the space of probability measures. Examples include the Wasserstein 2-norm, the χ^2 -divergence and the KL-divergence

$$W_2(\mu,\nu) = \left(\inf_{\pi \in \Pi(\mu,\nu)} \mathbb{E}_{\pi} \|x - y\|^2\right)^{\frac{1}{2}}, \quad \chi^2(\mu,\nu) = \mathsf{Var}_{\nu}\left(\frac{\rho_{\mu}}{\rho_{\nu}}\right),$$

$$\mathsf{KL}(\mu,
u) = \mathbb{E}_{\mu} \log \left(rac{
ho_{\mu}}{
ho_{
u}}
ight).$$

University of Groningen Langevin Dynamics January 23rd, 2024 2/10

• A **stochastic process** is a sequence (possibly continuous in time) of random variables. We denote these sequences by $(X_t)_t$, where t is the time coordinate.



- A **stochastic process** is a sequence (possibly continuous in time) of random variables. We denote these sequences by $(X_t)_t$, where t is the time coordinate.
- Brownian motion is a stochastic process $(B_t)_{t>0}$ such that

- A **stochastic process** is a sequence (possibly continuous in time) of random variables. We denote these sequences by $(X_t)_t$, where t is the time coordinate.
- Brownian motion is a stochastic process $(B_t)_{t\geq 0}$ such that $B_0=0$,

- A **stochastic process** is a sequence (possibly continuous in time) of random variables. We denote these sequences by $(X_t)_t$, where t is the time coordinate.
- Brownian motion is a stochastic process $(B_t)_{t\geq 0}$ such that $B_0=0$, (B_t) is almost surely continuous,

- A **stochastic process** is a sequence (possibly continuous in time) of random variables. We denote these sequences by $(X_t)_t$, where t is the time coordinate.
- Brownian motion is a stochastic process $(B_t)_{t\geq 0}$ such that $B_0=0$, (B_t) is almost surely continuous, (B_t) has independent increments

- A **stochastic process** is a sequence (possibly continuous in time) of random variables. We denote these sequences by $(X_t)_t$, where t is the time coordinate.
- Brownian motion is a stochastic process $(B_t)_{t\geq 0}$ such that $B_0=0$, (B_t) is almost surely continuous, (B_t) has independent increments and $B_{t+s}-B_t \sim \mathcal{N}(0,s)$.

- A **stochastic process** is a sequence (possibly continuous in time) of random variables. We denote these sequences by $(X_t)_t$, where t is the time coordinate.
- **Brownian motion** is a stochastic process $(B_t)_{t\geq 0}$ such that $B_0=0$, (B_t) is almost surely continuous, (B_t) has independent increments and $B_{t+s}-B_t\sim \mathcal{N}(0,s)$.

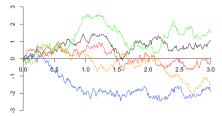


Figure: Brownian Motion. Image from the internet.

Langevin dynamics are governed by the stochastic differential equation

$$dX_t = -\nabla U(X_t)dt + \sqrt{2}dB_t,$$

where $U: \mathbb{R}^n \to \mathbb{R}$ is a differentiable potential function.

Langevin Dynamics

Langevin dynamics are governed by the stochastic differential equation

$$dX_t = -\nabla U(X_t)dt + \sqrt{2}dB_t,$$

where $U: \mathbb{R}^n \to \mathbb{R}$ is a differentiable potential function.

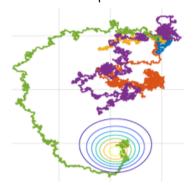


Figure: Particule following the Langevin Dynamics. Image from the internet.

University of Groningen Langevin Dynamics January 23rd, 2024 4 / 10

Consider the **Exact Langevin Dynamics** with initial condition $X_0 \sim \mu_0$

$$dX_t = -\nabla U(X_t)dt + \sqrt{2}dB_t.$$



Consider the **Exact Langevin Dynamics** with initial condition $X_0 \sim \mu_0$

$$dX_t = -\nabla U(X_t)dt + \sqrt{2}dB_t.$$

Its Euler-Murayama discretization **Discretized Langevin Dynamics** with initial condition $Y_0 \sim \mu_0$ and step size δ is given by

$$dY_t = -\nabla U(Y_{k\delta})dt + \sqrt{2}dB_t$$
 for $t \in [k\delta, (k+1)\delta]$.

Consider the **Exact Langevin Dynamics** with initial condition $X_0 \sim \mu_0$

$$dX_t = -\nabla U(X_t)dt + \sqrt{2}dB_t.$$

Its Euler-Murayama discretization **Discretized Langevin Dynamics** with initial condition $Y_0 \sim \mu_0$ and step size δ is given by

$$dY_t = -\nabla U(Y_{k\delta})dt + \sqrt{2}dB_t$$
 for $t \in [k\delta, (k+1)\delta]$.

The fully iterative **Langevin MCMC Algorithm** with initial condition $Z^0 \sim \mu_0$ and step size δ is then written as

$$Z^{k+1} = Z^k - \delta \nabla U(Z^k) dt + \sqrt{2\delta} \xi^k$$
 where $\xi^k \sim \mathcal{N}(0,1)$.

Consider the **Exact Langevin Dynamics** with initial condition $X_0 \sim \mu_0$

$$dX_t = -\nabla U(X_t)dt + \sqrt{2}dB_t.$$

Its Euler-Murayama discretization Discretized Langevin Dynamics with initial condition $Y_0 \sim \mu_0$ and step size δ is given by

$$dY_t = -\nabla U(Y_{k\delta})dt + \sqrt{2}dB_t$$
 for $t \in [k\delta, (k+1)\delta]$.

The fully iterative Langevin MCMC Algorithm with initial condition $Z^0 \sim \mu_0$ and step size δ is then written as

$$Z^{k+1} = Z^k - \delta \nabla U(Z^k) dt + \sqrt{2\delta} \xi^k$$
 where $\xi^k \sim \mathcal{N}(0, 1)$.

Since $B_{(k+1)\delta} - B_{t\delta} \sim \sqrt{\delta} \mathcal{N}(0,1)$, it holds that Z^k and $Y_{k\delta}$ are equivalent.

January 23rd, 2024

Discretized Langevin Dynamics:

$$dY_t = -\nabla U(Y_{k\delta})dt + \sqrt{2}dB_t$$
 for $t \in [k\delta, (k+1)\delta]$.

Discretized Langevin Dynamics:

$$dY_t = -\nabla U(Y_{k\delta})dt + \sqrt{2}dB_t$$
 for $t \in [k\delta, (k+1)\delta]$.

Theorem (Strong Convexity Result^a)

^aXiang Cheng and Peter Bartlett. "Convergence of Langevin MCMC in KL-divergence". In: *Algorithmic Learning Theory*. PMLR, 2018, pp. 186–211.

Suppose $U: \mathbb{R}^d \to \mathbb{R}$ is strongly convex and smooth.

Discretized Langevin Dynamics:

$$dY_t = -\nabla U(Y_{k\delta})dt + \sqrt{2}dB_t$$
 for $t \in [k\delta, (k+1)\delta]$.

Theorem (Strong Convexity Result^a)

^aXiang Cheng and Peter Bartlett. "Convergence of Langevin MCMC in KL-divergence". In: *Algorithmic Learning Theory*. PMLR. 2018, pp. 186–211.

Suppose $U: \mathbb{R}^d \to \mathbb{R}$ is strongly convex and smooth. Under mild conditions on μ_0, δ, k and $\varepsilon > 0$, $\mathsf{KL}(\mu_k \delta, \mu^*) \leq \varepsilon$,

Discretized Langevin Dynamics:

$$dY_t = -\nabla U(Y_{k\delta})dt + \sqrt{2}dB_t$$
 for $t \in [k\delta, (k+1)\delta]$.

Theorem (Strong Convexity Result^a)

^aXiang Cheng and Peter Bartlett. "Convergence of Langevin MCMC in KL-divergence". In: *Algorithmic Learning Theory*. PMLR. 2018, pp. 186–211.

Suppose $U: \mathbb{R}^d \to \mathbb{R}$ is strongly convex and smooth. Under mild conditions on μ_0, δ, k and $\varepsilon > 0$, $\mathsf{KL}(\mu_{k\delta}, \mu^*) \le \varepsilon$, where μ^* is the stationary distribution of the **Exact Langevin Dynamics**

Discretized Langevin Dynamics:

$$dY_t = -\nabla U(Y_{k\delta})dt + \sqrt{2}dB_t$$
 for $t \in [k\delta, (k+1)\delta]$.

Theorem (Strong Convexity Result^a)

^aXiang Cheng and Peter Bartlett. "Convergence of Langevin MCMC in KL-divergence". In: *Algorithmic Learning Theory*. PMLR. 2018, pp. 186–211.

Suppose $U: \mathbb{R}^d \to \mathbb{R}$ is strongly convex and smooth. Under mild conditions on μ_0, δ, k and $\varepsilon > 0$, $\mathsf{KL}(\mu_k \delta, \mu^*) \le \varepsilon$, where μ^* is the stationary distribution of the **Exact Langevin Dynamics** and $\rho_k \delta$ is the distribution of $Y_k \delta$ given by the **Discretized Langevin Dynamics**.

Discretized Langevin Dynamics:

$$dY_t = -\nabla U(Y_{k\delta})dt + \sqrt{2}dB_t$$
 for $t \in [k\delta, (k+1)\delta]$.

Theorem (Strong Convexity Result^a)

^aXiang Cheng and Peter Bartlett. "Convergence of Langevin MCMC in KL-divergence". In: Algorithmic Learning Theory. PMLR. 2018, pp. 186–211.

Suppose $U: \mathbb{R}^d \to \mathbb{R}$ is strongly convex and smooth. Under mild conditions on μ_0, δ, k and $\varepsilon > 0$, $\mathsf{KL}(\mu_{k\delta}, \mu^*) \leq \varepsilon$, where μ^* is the stationary distribution of the **Exact Langevin Dynamics** and $\rho_{k\delta}$ is the distribution of $Y_{k\delta}$ given by the **Discretized Langevin Dynamics**.

Note that since Z^k and $Y_{k\delta}$ are equivalent, the above also proves convergence in distribution of the Langevin MCMC Algorithm.

University of Groningen

Continuous Results

In the deterministic case (zero noise), the Langevin Dynamics boil down to

$$\frac{dX(t)}{dt} = -\nabla U(X(t)).$$

Continuous Results

In the deterministic case (zero noise), the Langevin Dynamics boil down to

$$\frac{dX(t)}{dt} = -\nabla U(X(t)).$$

Let ρ_t denote the density of X_t . The Langevin Dynamics may be rewritten using the Fokker-Planck equation as

$$\frac{\partial \rho_t}{\partial t} = \nabla \cdot (\rho_t \nabla U) + \Delta \rho_t.$$

Continuous Results

In the deterministic case (zero noise), the Langevin Dynamics boil down to

$$\frac{dX(t)}{dt} = -\nabla U(X(t)).$$

Let ρ_t denote the density of X_t . The Langevin Dynamics may be rewritten using the Fokker-Planck equation as

$$\frac{\partial \rho_t}{\partial t} = \nabla \cdot (\rho_t \nabla U) + \Delta \rho_t.$$

Theorem (Convergence in Continuous Time^a)

^aStephen Tu. "On the exponential convergence of Langevin diffusions: from deterministic to stochastic stability". In: GitHub (2022).

If there exists a suitable Lyapunov function for the deterministic system, then, for any initial measure, we achieve linear convergence towards the stationary distribution (in the χ^2 -divergence).

JKO Scheme

Jordan, Kinderlehrer and Otto established the following algorithm

$$\rho_{\delta}^{k+1} = \underset{\rho}{\operatorname{argmin}} \left\{ \delta F(\rho) + \frac{1}{2} W_2(\rho_{\delta}^k, \rho)^2 \right\},$$

where $\delta > 0$ is a fixed step size, F is the free energy functional depending on the potential U.

JKO Scheme

Jordan, Kinderlehrer and Otto established the following algorithm

$$\rho_{\delta}^{k+1} = \underset{\rho}{\operatorname{argmin}} \left\{ \delta F(\rho) + \frac{1}{2} W_2(\rho_{\delta}^k, \rho)^2 \right\},\,$$

Fokker-Planck Equation

where $\delta > 0$ is a fixed step size, F is the free energy functional depending on the potential U.

Theorem (Strong Convergence to the True Solution^a)

^aRichard Jordan, David Kinderlehrer, and Felix Otto. "The variational formulation of the Fokker-Planck equation". In: SIAM Journal on Mathematical Analysis 29.1 (1998).

As $\delta \to 0$, the JKO iterations converge strongly to the unique true solution of the Fokker-Planck equation in L^1 -norm.

JKO Scheme

Jordan, Kinderlehrer and Otto established the following algorithm

$$\rho_{\delta}^{k+1} = \underset{\rho}{\operatorname{argmin}} \left\{ \delta F(\rho) + \frac{1}{2} W_2(\rho_{\delta}^k, \rho)^2 \right\},\,$$

where $\delta > 0$ is a fixed step size, F is the free energy functional depending on the potential U.

Theorem (Strong Convergence to the True Solution^a)

^aRichard Jordan, David Kinderlehrer, and Felix Otto. "The variational formulation of the Fokker-Planck equation". In: SIAM Journal on Mathematical Analysis 29.1 (1998).

As $\delta \to 0$, the JKO iterations converge strongly to the unique true solution of the Fokker-Planck equation in L^1 -norm.

Note that under the assumption on the previous slide, the true solution converges to the stationary distribution. 4日 (日本) (日本) (日本) (日本)

The space of probability measures can be equipped with a differentiable structure through **Otto calculus**.

University of Groningen Langevin Dynamics January 23rd, 2024

¹Marc Lambert et al. "Variational inference via Wasserstein gradient flows". In: *Advances in Neural Information Processing Systems* 35 (2022), pp. 14434–14447. §

Wasserstein Gradient Flows

The space of probability measures can be equipped with a differentiable structure through **Otto calculus**.

Example

For
$$F(\rho_t) = \mathsf{KL}(\rho_t, \rho)$$
, we have $\nabla_W F(\rho_t) = \nabla \log \frac{\rho_t}{\rho}(\cdot)$.

For
$$F(\rho_t) = \chi^2(\rho_t, \rho)$$
, we have $\nabla_W F(\rho_t) = 2\nabla \frac{\rho_t}{\rho}(\dot{\cdot})$.

University of Groningen Langevin Dynamics January 23rd, 2024

Wasserstein Gradient Flows

The space of probability measures can be equipped with a differentiable structure through **Otto calculus**.

Example

For
$$F(\rho_t) = \mathsf{KL}(\rho_t, \rho)$$
, we have $\nabla_W F(\rho_t) = \nabla \log \frac{\rho_t}{\rho}(\cdot)$.
For $F(\rho_t) = \chi^2(\rho_t, \rho)$, we have $\nabla_W F(\rho_t) = 2\nabla \frac{\rho_t}{\rho}(\cdot)$.

The JKO scheme can be viewed as a discretisation of the following deterministic gradient flow in Wasserstein space¹

$$\dot{X}_t = -\nabla_W F(\rho_t)(X_t).$$

University of Groningen Langevin Dynamics January 23rd, 2024

¹Marc Lambert et al. "Variational inference via Wasserstein gradient flows". In: Advances in Neural Information Processing Systems 35 (2022), pp. 14434–14447.

■

Wasserstein Gradient Flows

The space of probability measures can be equipped with a differentiable structure through Otto calculus.

Example

For
$$F(\rho_t) = \mathsf{KL}(\rho_t, \rho)$$
, we have $\nabla_W F(\rho_t) = \nabla \log \frac{\rho_t}{\rho}(\cdot)$.
For $F(\rho_t) = \chi^2(\rho_t, \rho)$, we have $\nabla_W F(\rho_t) = 2\nabla \frac{\rho_t}{\rho}(\cdot)$.

The JKO scheme can be viewed as a discretisation of the following deterministic gradient flow in Wasserstein space¹

$$\dot{X}_t = -\nabla_W F(\rho_t)(X_t).$$

In this case, standard optimisation techniques such as Gradient Descent, Newton Method, Proximal Method, etc. apply.

University of Groningen Langevin Dynamics January 23rd, 2024

¹Marc Lambert et al. "Variational inference via Wasserstein gradient flows". In: Advances in Neural Information Processing Systems 35 (2022), pp. 14434–14447

Any questions?

